

Homework Q's

$$4.2 \quad f(\vec{u}, \vec{v}) = \underbrace{\vec{u}^T A \vec{u}} + \underbrace{\vec{v}^T (B \vec{u})} + c$$

use defns.

$$\vec{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} \quad A = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \\ & \ddots \end{bmatrix}$$

12.3

$$\frac{1}{n-1} \sum_{i=1}^n (\vec{x}_i - \vec{\mu})(\vec{x}_i - \vec{\mu})^T \quad \vec{x}_i \quad 15\text{-dim}$$

outer product = 15 x 15

$$\begin{bmatrix} \vec{\mu} & \dots & \vec{\mu} \\ 1 & & 1 \end{bmatrix}$$

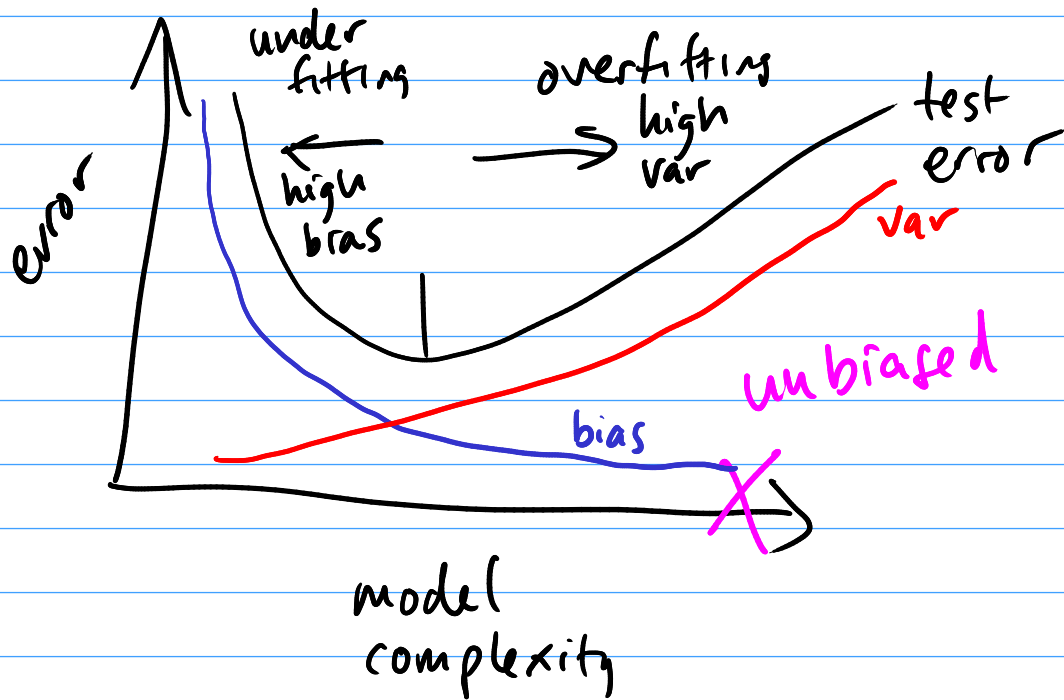
broadcasting

`A = np.array(...)`

`X - mu[i, np.newaxis]`
np.repeat

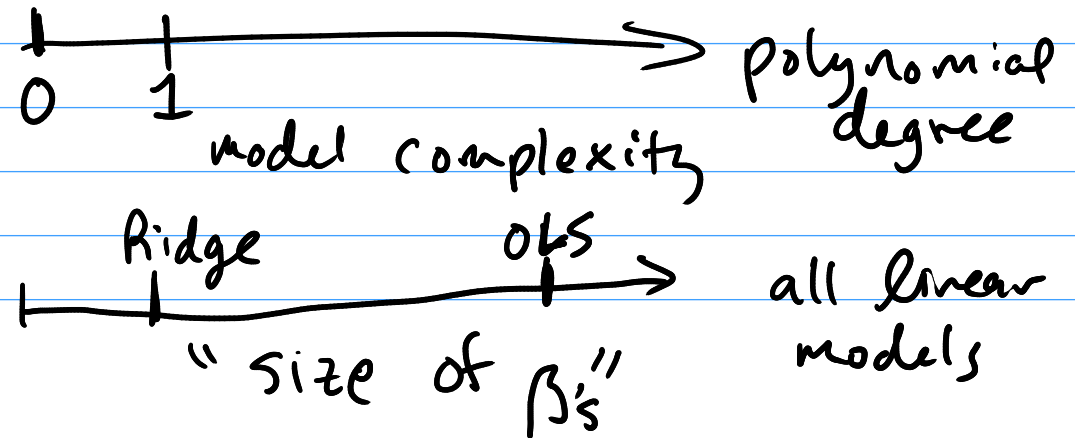
`A.shape (100, 1) (100, 1)`

Problem 11 \rightarrow new PDF



big coefficients
on polynomials
 β 's $\gg 100$

Ridge Regression



Ordinary least squares (OLS) is unbiased

$$\vec{y} = X\vec{\beta}^* + \vec{\epsilon}$$

↑ true model

noise

up. random. vander
Gaussian random vars
 $E[\vec{\epsilon}] = 0$

Assume:
 $X^T X$ not
singular

$$\begin{aligned}\vec{\beta} &= (X^T X)^{-1} X^T \vec{y} = (X^T X)^{-1} X^T (X\vec{\beta}^* + \vec{\epsilon}) \\ &= \underbrace{(X^T X)^{-1} X^T X}_{\text{green}} \vec{\beta}^* + \underbrace{(X^T X)^{-1} X^T}_{\text{red}} \vec{\epsilon} \\ &= \vec{\beta}^* + (X^T X)^{-1} X^T \vec{\epsilon}\end{aligned}$$

$$E[\vec{\beta}] = \vec{\beta}^* + \underbrace{(X^T X)^{-1} X^T E[\vec{\epsilon}]}_{\text{crossed out}}$$

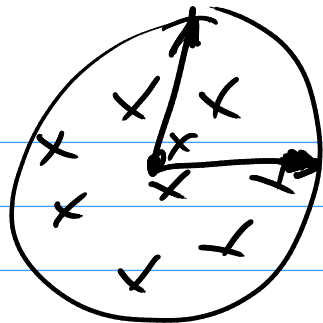
averaging over noise,
OLS estimate = truth

$$\text{Bias} = E[\vec{\beta}] - \vec{\beta}^*$$

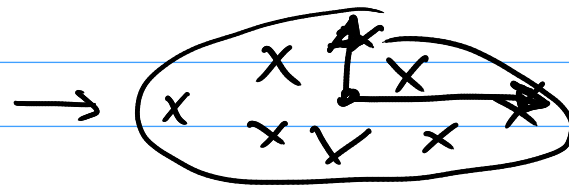
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Observations

(Cholesky decomposition
generating correlated
Gaussians)



$$\sigma_1 \approx \sigma_2$$



$$\sigma_1 \approx 5\sigma_2$$

same
rough size



$$\sigma_1 \gg \sigma_2$$

$$\sigma_1 \approx 100\sigma_2$$

small
 σ_2

$$\vec{\beta}_{OLS} = \sum_{i=1}^{\text{rank}(X)} \vec{v}_i$$

$$\left(\frac{\vec{u}_i^T \vec{y}}{\sigma_i} \right)$$

has noise

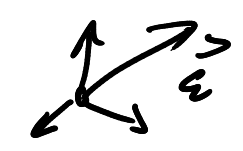
w_i

$\frac{1}{\text{small}} = \text{big}$

noise = equally shared
among the components

Correlations in X
 \iff small s.v.'s

If linear model is true:

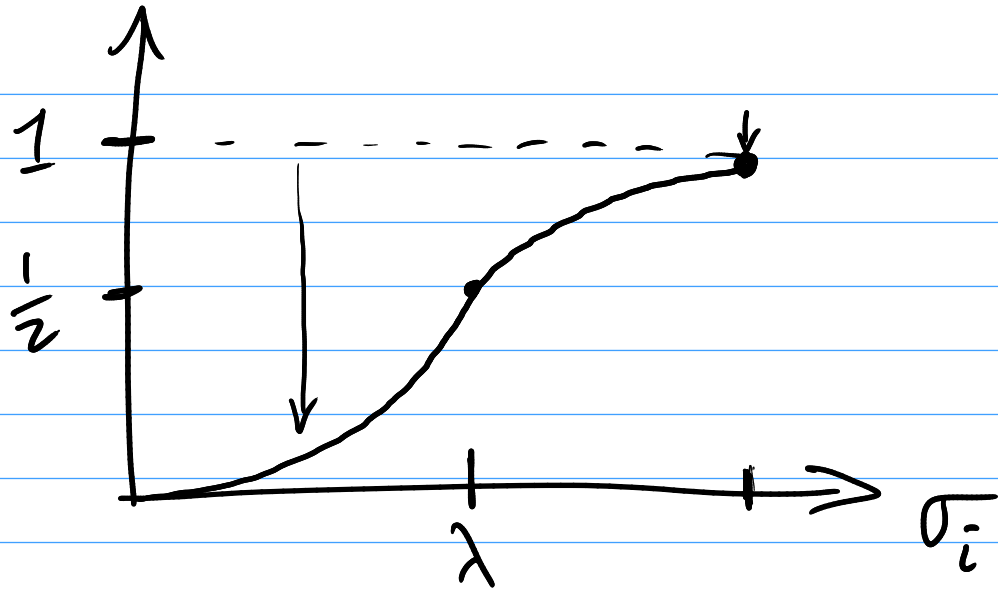
$$w_i = \underbrace{\vec{v}_i^T \vec{\beta}^*}_{i^{\text{th}} \text{ component } \vec{\beta}^* \text{ in } V \text{ basis}} + \frac{\vec{u}_i^T \vec{\epsilon}}{\sigma_i} \leftarrow \begin{array}{l} \text{i.i.d.} \\ \text{effect of noise} \end{array}$$


$$\vec{\beta}_{\text{ridge}} = \sum_{i=1}^{\text{rank}(X)} \vec{v}_i \underbrace{\left(\frac{\vec{u}_i^T \vec{y}}{\sigma_i + \lambda} \right)}_{w_i}, \quad w_i = \underbrace{\left(\frac{\sigma_i}{\sigma_i + \lambda} \right)}_{\text{plot}} \vec{v}_i^T \vec{\beta}^* + \frac{\vec{u}_i^T \vec{\epsilon}}{\sigma_i + \lambda}$$

λ ridge parameter, must be tuned for dataset / scenario

$\sigma_i > \lambda$: not much effect

$\sigma_i < \lambda$: have strong effect on those components



$$\frac{\sigma_i}{\sigma_i + \lambda} = \frac{1}{1 + \frac{\lambda}{\sigma_i}}$$

Ridge : add bias ($\lambda=0$ no bias, OLS)
reduce variance

Extra: How to get w_i formula

$$w_i = \frac{\vec{u}_i^T \vec{y}}{\sigma_i} = \frac{\vec{u}_i^T (X \vec{\beta}^* + \vec{\epsilon})}{\sigma_i} \quad \text{using linear assumption}$$

$$= \frac{\vec{u}_i^T (U S V^T \vec{\beta}^* + \vec{\epsilon})}{\sigma_i} \quad \text{using } X = U S V^T$$

$$= \underbrace{\vec{u}_i^T U S V^T \vec{\beta}^* \left(\frac{1}{\sigma_i}\right)}_{\vec{u}_i^T U = \begin{pmatrix} 0 & 0 & & \\ & 1 & & \\ & & \ddots & \\ & & & 0 \end{pmatrix}} + \frac{\vec{u}_i^T \vec{\epsilon}}{\sigma_i} = \underbrace{\vec{v}_i^T \vec{\beta}^*}_{i^{\text{th}} \text{ component in } V \text{ basis}} + \underbrace{\frac{\vec{u}_i^T \vec{\epsilon}}{\sigma_i}}_{\text{noise term}}$$

So it selects i^{th} singular vector, i.e.

$$\vec{u}_i^T U S V^T \vec{\beta}^* = \sigma_i \vec{v}_i^T \vec{\beta}^*$$