

Questions about HW 2?

$$\vec{x}^T \vec{y} = \vec{y}^T \vec{x}$$

$$\vec{v}^T B \vec{u} = \vec{u}^T B^T \vec{v}$$

scalar

Taking derivatives
or gradients

→ see video

$$\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_d \end{bmatrix}$$

$$\left(\nabla_{\vec{x}} C \right)_i = \frac{\partial C}{\partial x_i} = \sum_j (\dots) \frac{\partial x_j}{\partial x_i}$$

Reference to eqn.

Linear algebra review

$$\begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$$

- Tuesday 10/6 at noon
- will be recorded

$$\underline{X} = \begin{bmatrix} 1 & 2 \\ -1 & 1 \end{bmatrix}, \quad \vec{y} = \begin{bmatrix} .5 \\ 0 \end{bmatrix}$$

$$\underline{X}^T (\underline{X} \vec{\beta} \approx \vec{y})$$

normal
eqns.

$$= \underline{X}^T \underline{X} \vec{\beta} = \underline{X}^T \vec{y}$$

least-squares $\vec{\beta}$

$$C = \|\underline{X} \vec{\beta} - \vec{y}\|^2$$

$$\nabla_{\vec{\beta}} (\text{cost}) = 0$$

$$= 2 \underline{X}^T \underline{X} \vec{\beta} - 2 \underline{X}^T \vec{y}$$

- 1) cost function \rightarrow minimize ... zero gradient
- 2) compute gradient, set = 0
- 3) that gives normal eqns.

Last time

$$\vec{\beta}^* = \arg \min_{\vec{\beta}} \|\underline{X}\vec{\beta} - \vec{y}\|^2$$

"vector $\vec{\beta}$ argument that minimizes"

$$\text{SVD of } \underline{X} = U S V^T$$

$$\vec{\beta}^* = \underline{X}^T \vec{y} = V S^T U^T \vec{y} = \sum_{i=1}^{\text{rank}(\underline{X})} \vec{v}_i \left(\frac{\vec{u}_i^T \vec{y}}{\sigma_i} \right)$$

solves normal equations

Uses of SVD:

- pseudoinverse, solves linear least-squares
- low-rank approximation

given X find $X_r = \arg \min_{X'} \|X - X'\|$ where $\text{rank}(X') = r$

$$X = U S V^T$$

$$\text{rank}(X) > r$$

$$X_r = \sum_{i=1}^r \vec{u}_i \vec{v}_i^T \sigma_i$$

same as setting $\sigma_i, i > r, = 0$
keep r largest singular vectors

$$\|\cdot\|_{\text{Fro}} = \sqrt{\sum_{i,j} X_{i,j}^2}$$

$$\|\cdot\|_2$$

- PCA principal components analysis
unsupervised learning method
(no labels)

$$\Sigma \begin{matrix} (n \times d) \end{matrix} = \begin{bmatrix} - \vec{x}_1 - \\ \vdots \\ - \vec{x}_n - \end{bmatrix}$$

$$\Sigma' = \underbrace{\begin{bmatrix} - \vec{x}_1 - \\ \vdots \\ - \vec{x}_n - \end{bmatrix}}_{r < d}$$

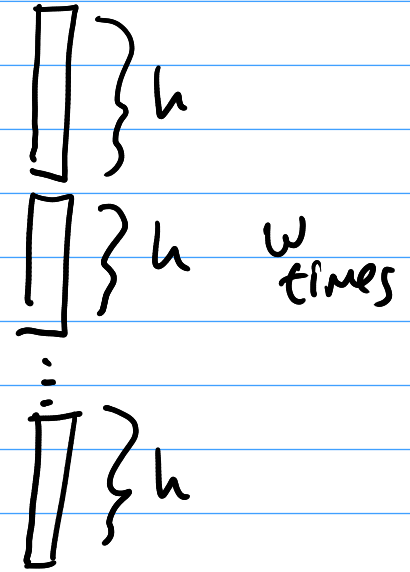
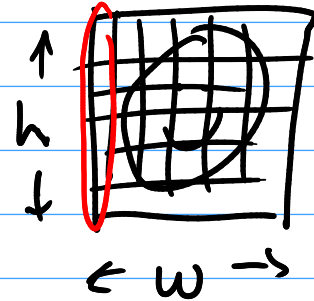
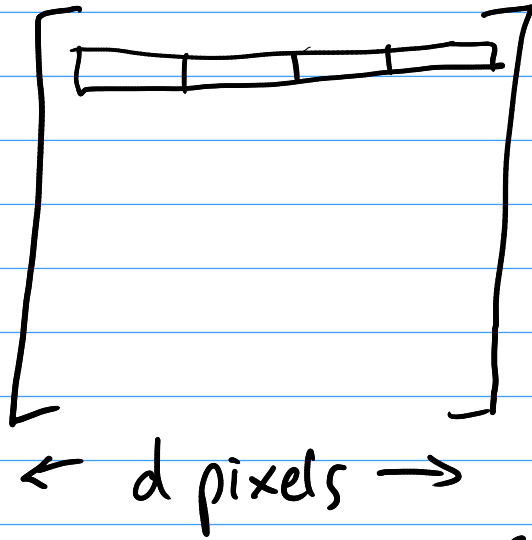
dimension reduction

pick some new dimension
 $r < d$
to reduce to

$$d = w \cdot h$$

ex/
 \bar{X}

= n people
↓



PCA

1. Subtract off mean

$$32 \times 32 = 1024$$

$$\vec{\mu} = \frac{1}{n} \sum_{i=1}^n \vec{x}_i$$

2. take SVD of $(\bar{X} - \vec{1} \vec{\mu}^T)$

mean-subtracted
matrix

matrix w/ $\vec{\mu}^T$ in every row

call this matrix Y

$$Y = U S V^T$$

$(n \times d)$ $(n \times n)$ $(d \times d)$
 Y U S V^T

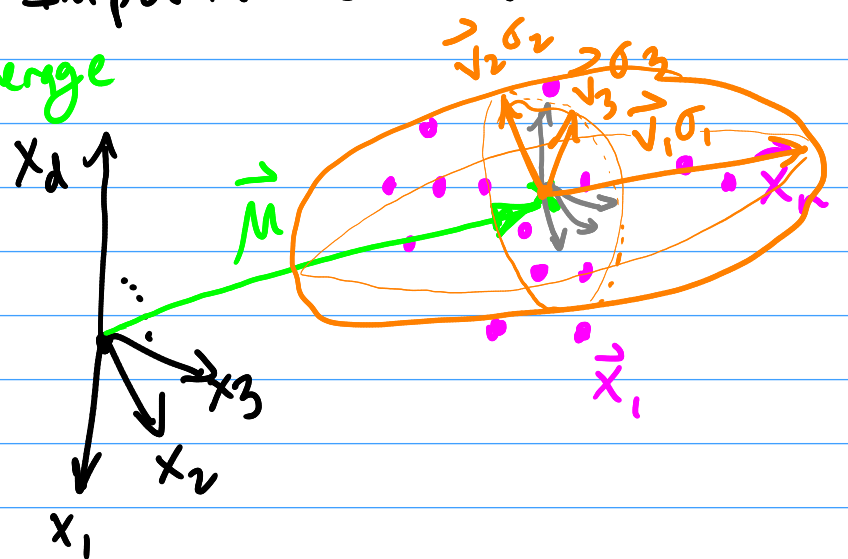
$$Y^T Y = V S^2 V^T$$

columns \vec{v}_i of V

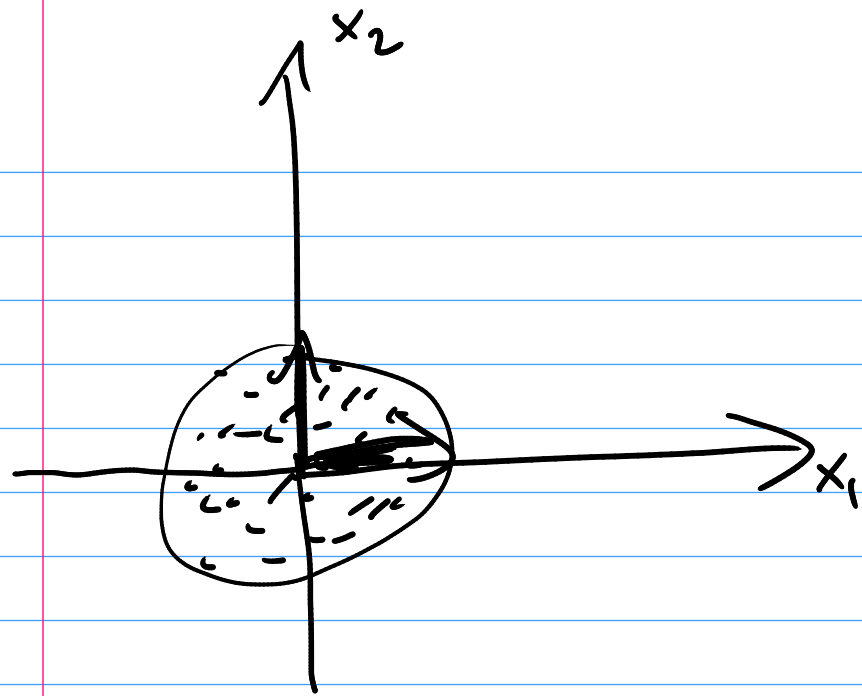
Defn: principal components of \bar{X} as the eigenvectors of $Y^T Y$ (covariance matrix) with "importance weightings" equal to the eigenvalues

Importance here means variance captured by i^{th} component

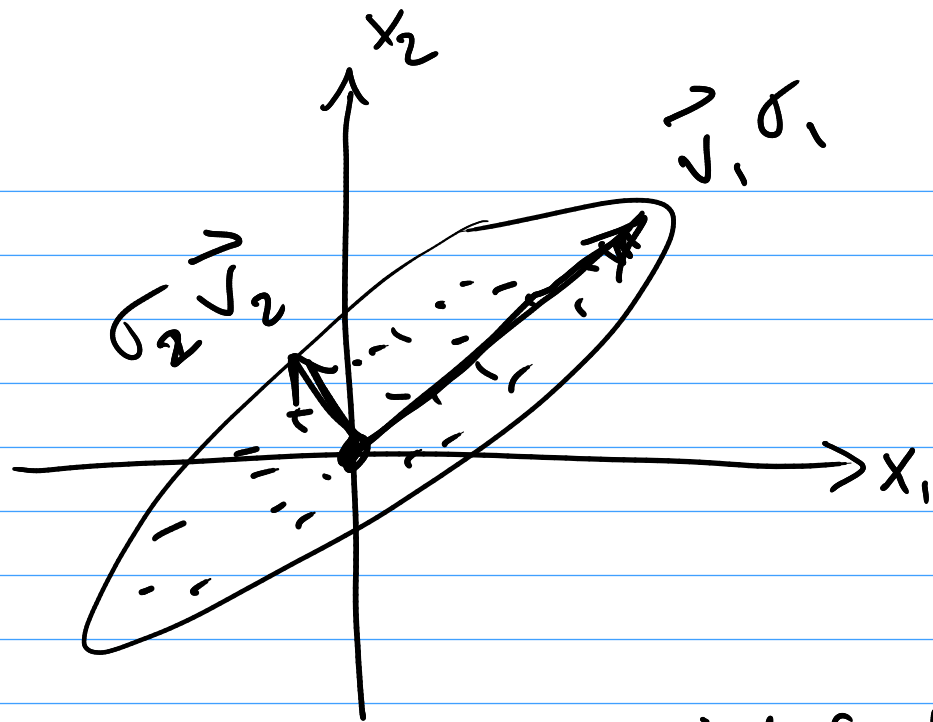
$\vec{\mu}$ = average



- Subtracting mean = moving origin to center of data
- SVD gives directions of axes of the ellipse \vec{v}_i
- Length of axes σ_i
variance σ_i^2



perfectly spherical data,
any orthonormal basis V works
(use coordinate axes)



any kind of elliptic shape to data,
you end up with unique axes

Fraction of variance explained $\left(\sigma_i = \text{standard deviation in } i^{\text{th}} \text{ direction} \right)$

$$\frac{\sigma_1^2}{\sum_j \sigma_j^2} = \text{fraction of variance explained by } 1^{\text{st}} \text{ component}$$

(can replace σ_1 by σ_i for i^{th} component)

$$\frac{\sum_{i=1}^r \sigma_i^2}{\sum_{j=1}^{\text{rank}(X)} \sigma_j^2} = \text{fraction of variance explained by components } 1, 2, \dots, r \text{ together}$$