

In this math $\vec{\beta} \in \mathbb{R}^d$

$$c, \vec{\beta}_{\text{lasso}} = \arg \min_{\vec{\beta}, c} \sum_{i=1}^n \left(\vec{x}_i^T \vec{\beta} + c - y_i \right)^2 + \lambda \sum_{i=1}^d |\beta_i|$$

$$c = \frac{1}{n} \sum_{i=1}^n \left(y_i - \underbrace{\sum_{j=1}^d X_{ij} \beta_j}_{\text{no intercept}} \right)$$

Math:

- 1-based
- 0-based code

$$b_i = 2 \sum_{j=1}^n X_{ji} \left(y_j - c - \sum_{\substack{k=1 \\ k \neq i}}^d X_{jk} \beta_k \right)$$

$$\begin{bmatrix} c \\ \vec{\beta} \end{bmatrix}$$

residual w/o using i^{th} predictor

Today: neural networks

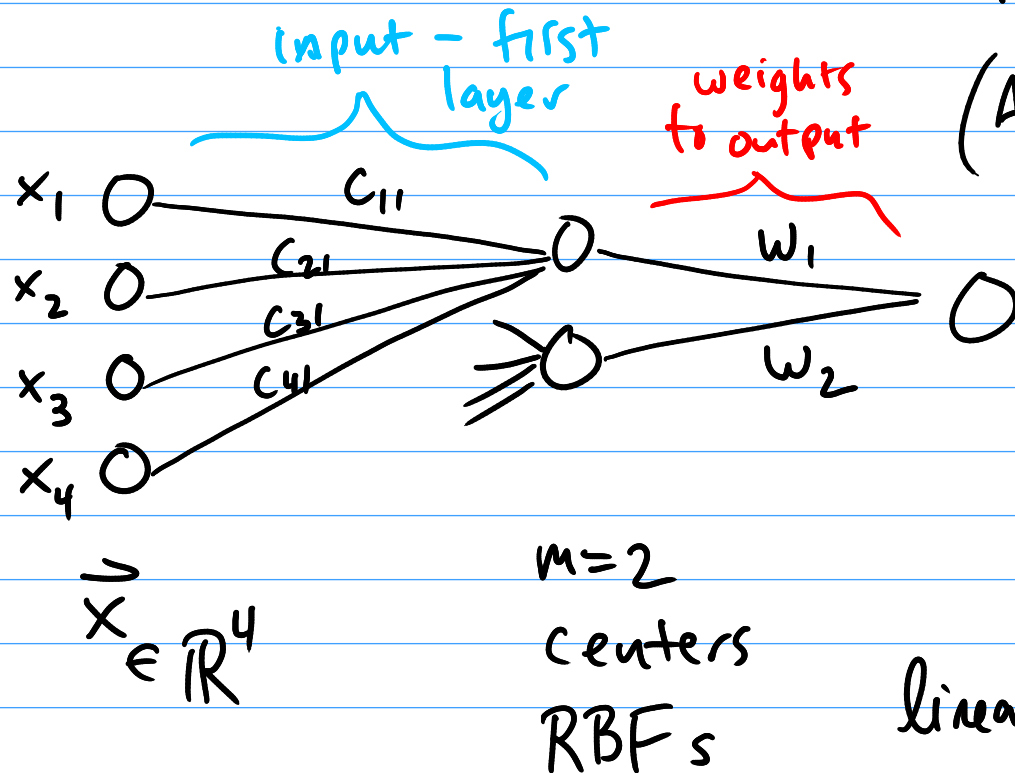
Tomorrow:
in-class HW help

Goals: functional form (2-layer)
where neuro connection comes from
RBF networks

RBF networks

$$f(\vec{x}) = \sum_{i=1}^m w_i g(\underbrace{\|\vec{x} - \vec{c}_i\|}_{\text{RBF function}})$$

i^{th} center
↓



(Artificial) Neural networks (NNs) relax the RBF constraint

$$f(\vec{x}) = \sum_{i=1}^m \underbrace{w_i}_{\text{Weights}} g(\vec{x}, \underbrace{\vec{c}_i}_{\text{arbitrary nonlinear function of } \vec{x} \text{ and parameters } \vec{c}_i})$$

Weights ←

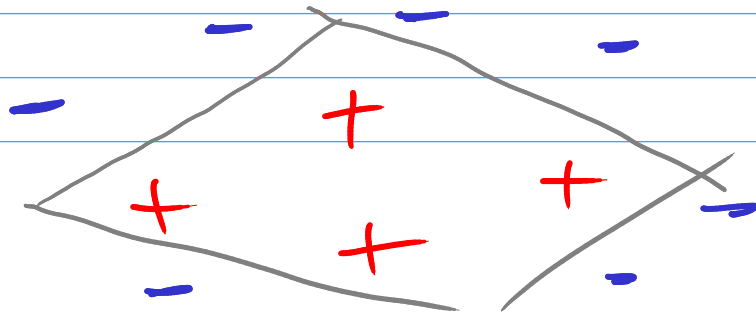
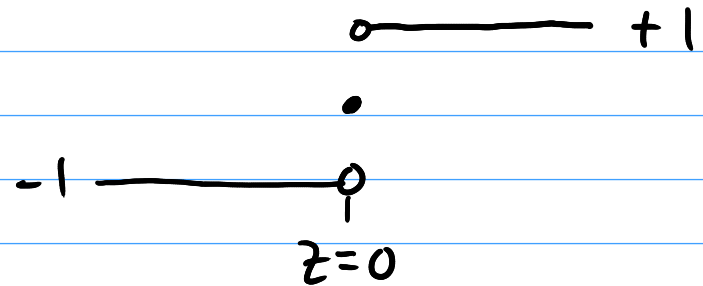
Often $g(\vec{x}, \vec{c}_i) = g(\underbrace{\vec{c}_i^T \vec{x}}_{\text{dot product}}) = g(\underbrace{z}_{\text{scalar}})$

Usually $g = \text{thresholded nonlinearity}$

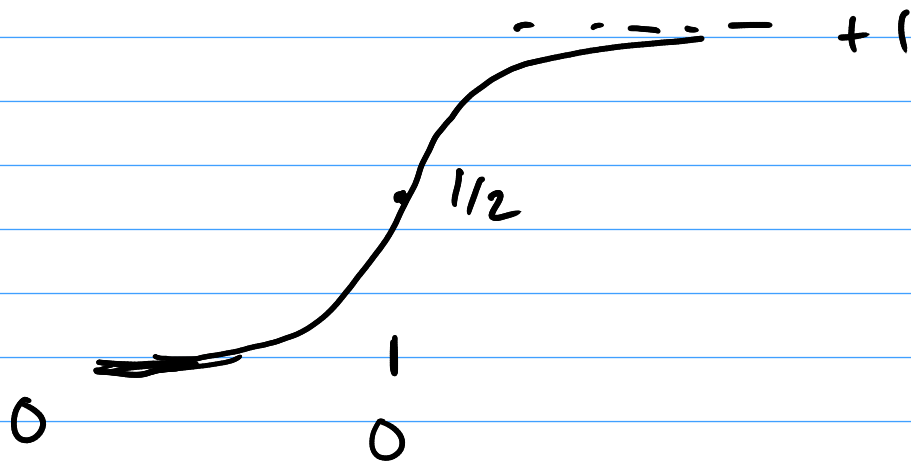
$$g(z) = \text{sgn}(z)$$

$$= \text{sgn}(\vec{c}^T \vec{x})$$

predictions of linear classifier



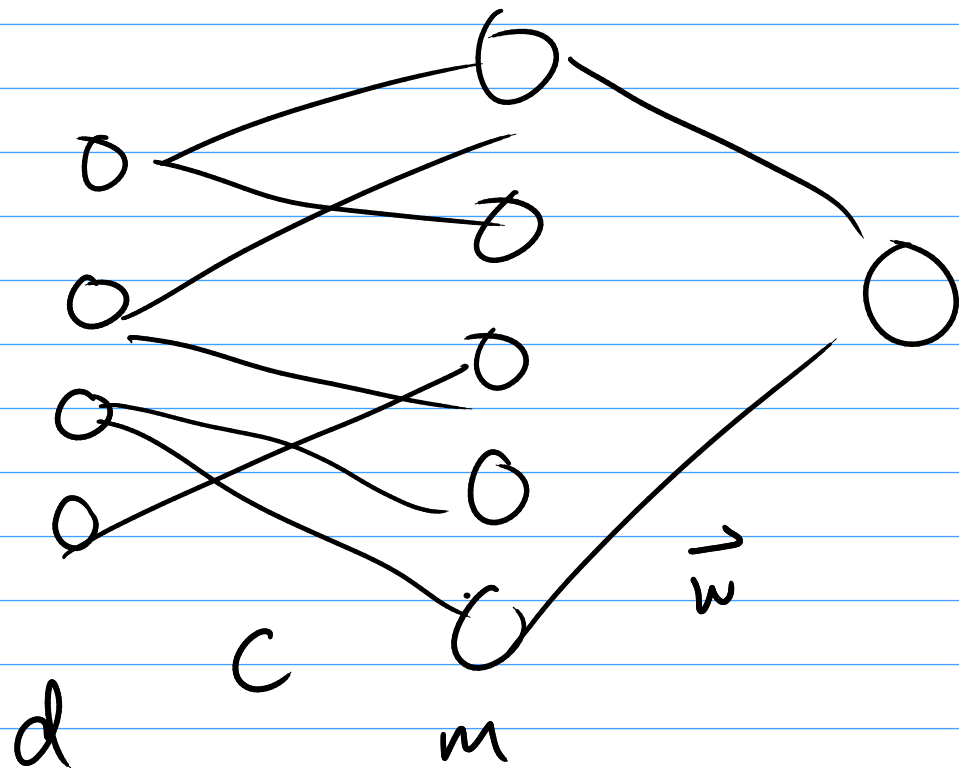
More realistic: Saturating nonlinearity



logistic regression
modeled $\Pr[Y=+1]$

$$g(z) = \frac{1}{1 + e^{-z}}$$

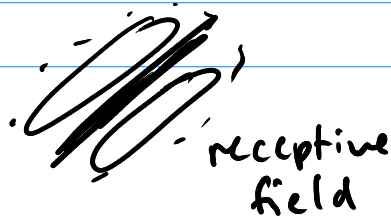
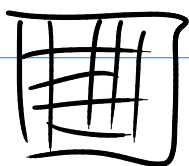
Design m units, nonlinearity



$$f(\vec{x}) = \sum_{i=1}^m w_i g(\vec{c}_i^T \vec{x})$$

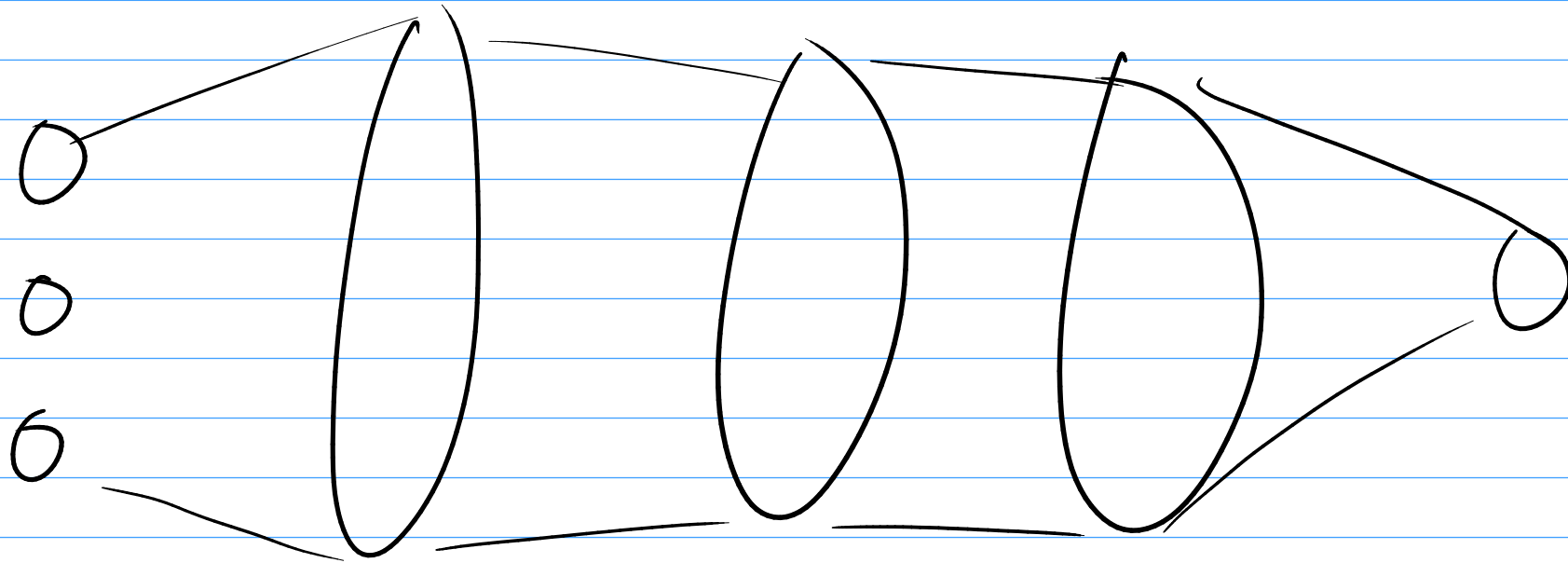
Similar to RBFs:

If C is fixed,
training \vec{w} is just
like training a
linear model



- area of research
- study structures in C
+ functions you can learn

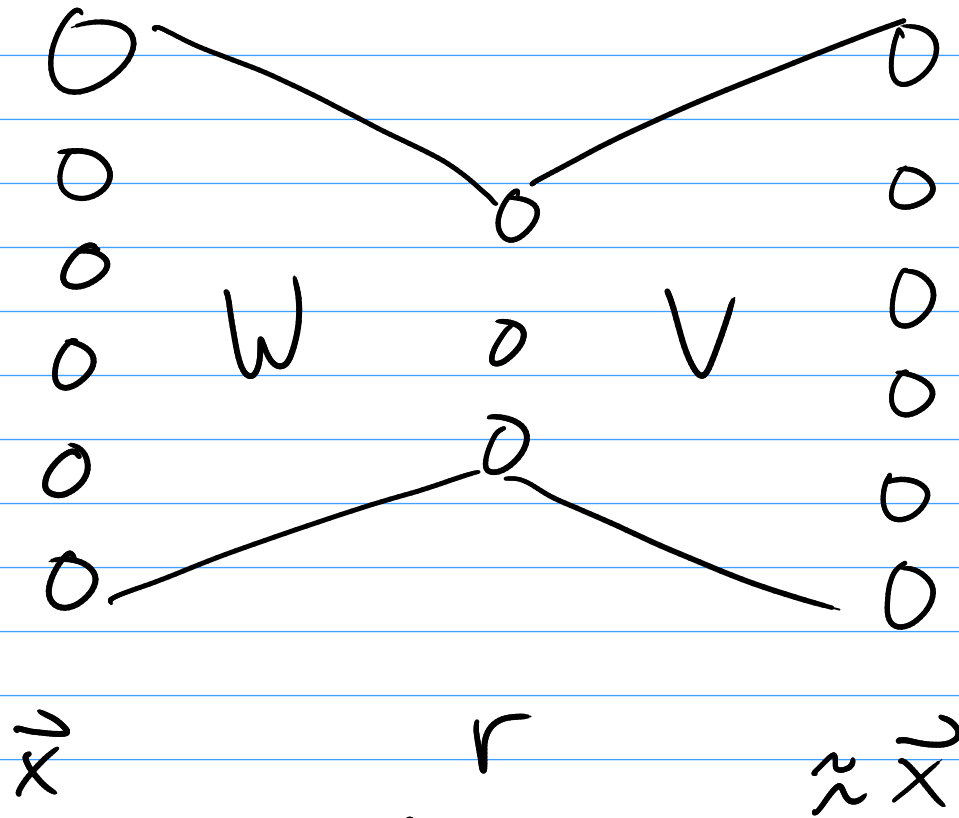
deep learning



In practice:

- train C's SGD
- try lots of layers (1, 2, ...) diff architectures
- still working on theory

autoencoder

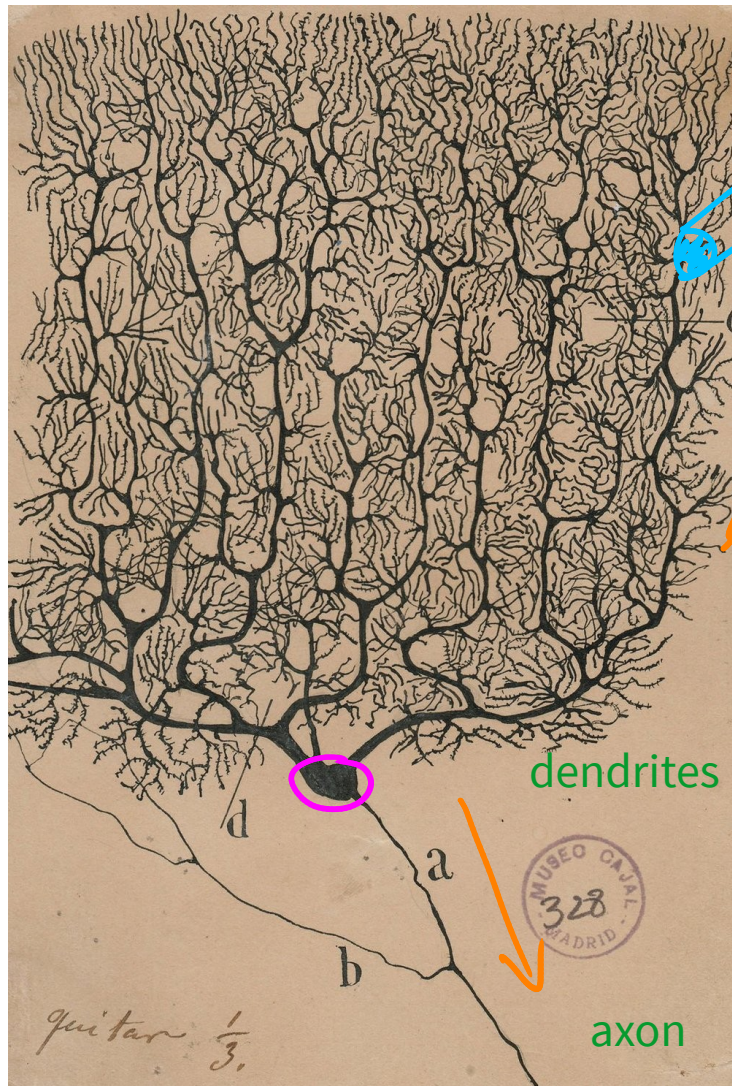


linear

$$g(z) = z$$

Supporting slides, networks intro

CSCI 471/571 Fall 2020



Electrode

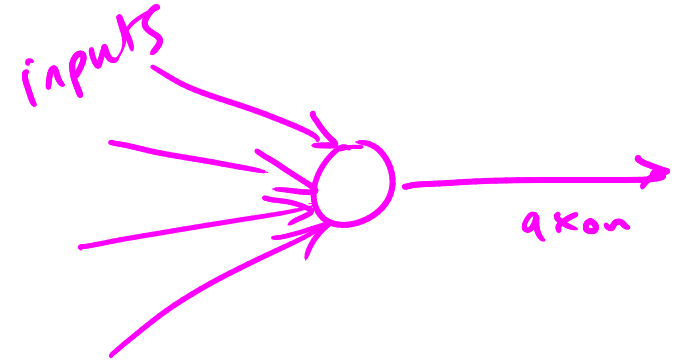
Drawing of a Purkinje neuron
by Santiago Ramón y Cajal

Golgi (silver) staining technique
only labels a few
neurons

inputs

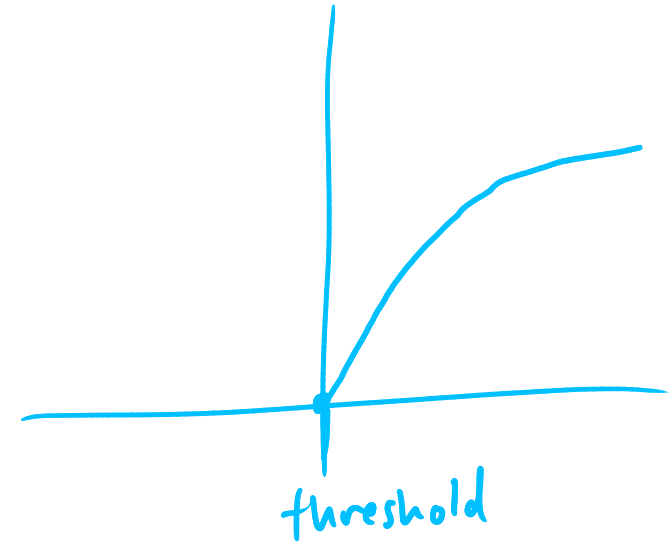
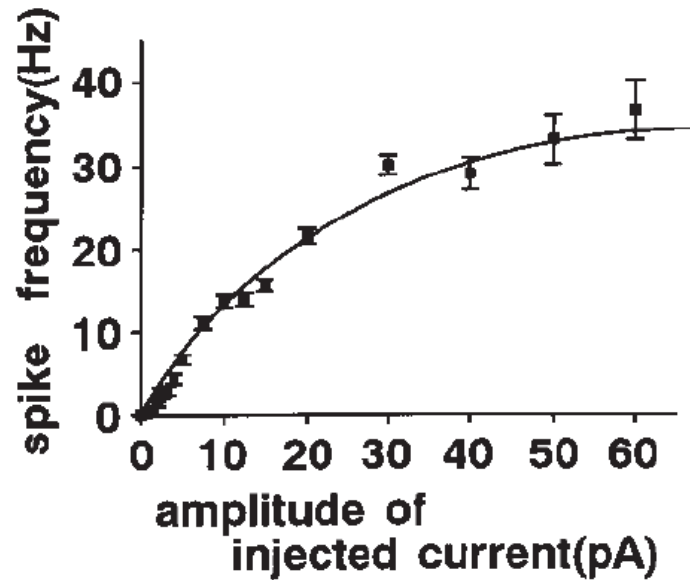
dendrites

axon

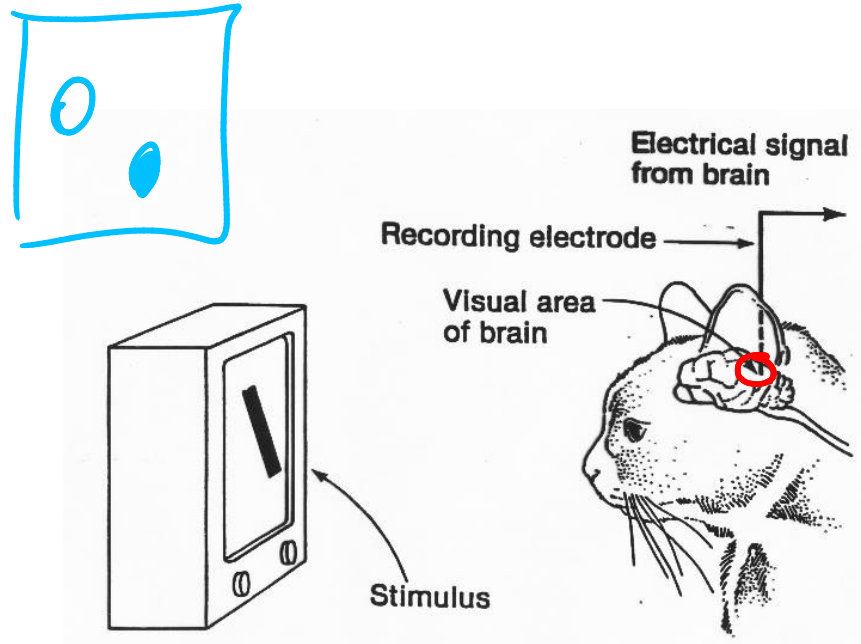


Nonlinearities in real neurons

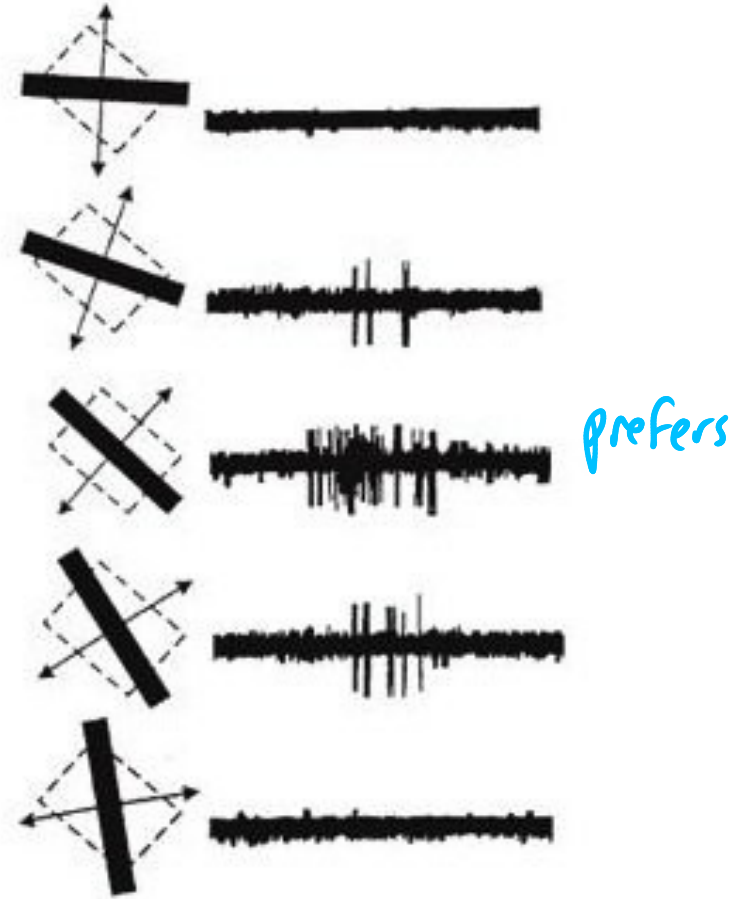
(frog ones, in fact)



Real neurons are selective to inputs



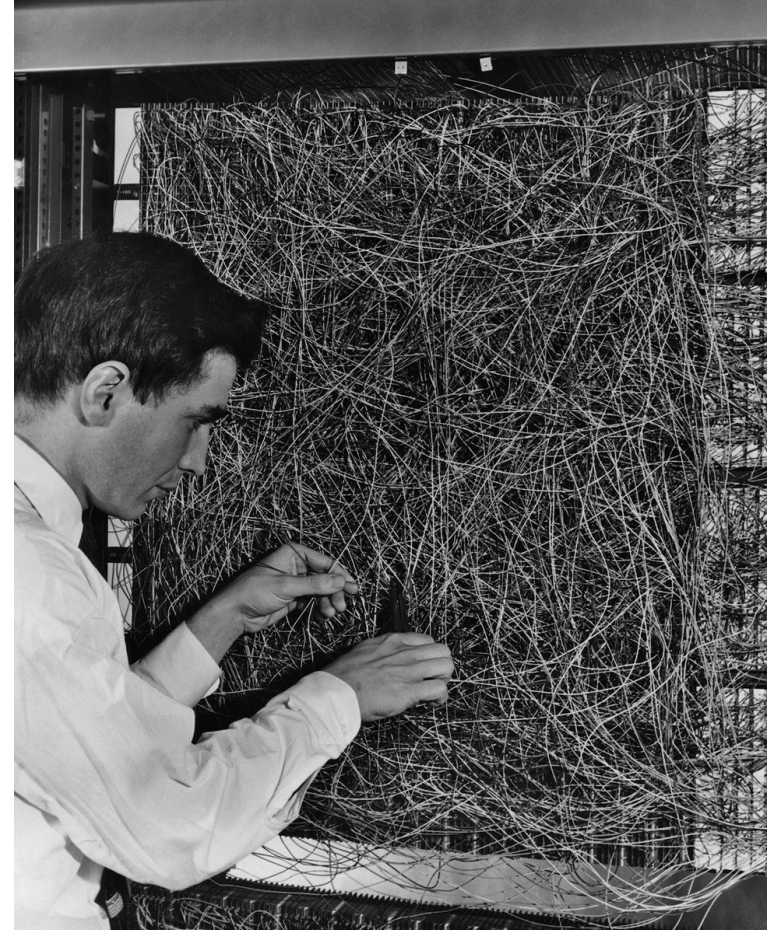
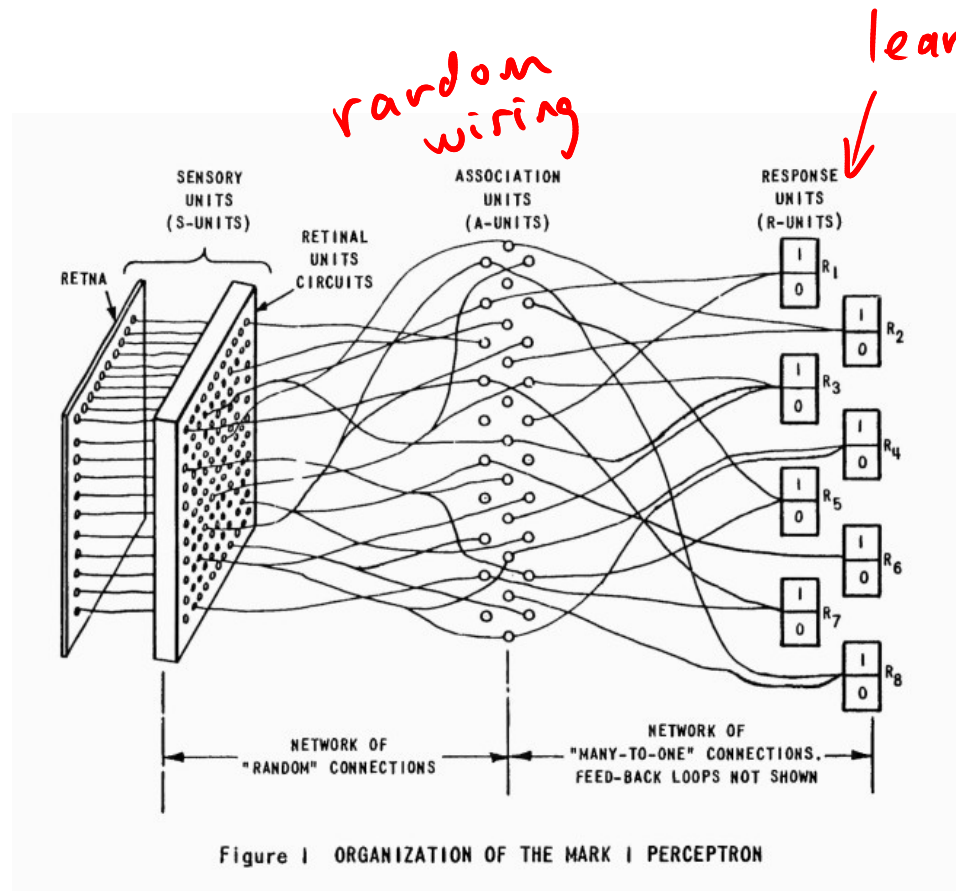
Hubel & Wiesel
late '50s onward



First artificial neural network

Perceptron

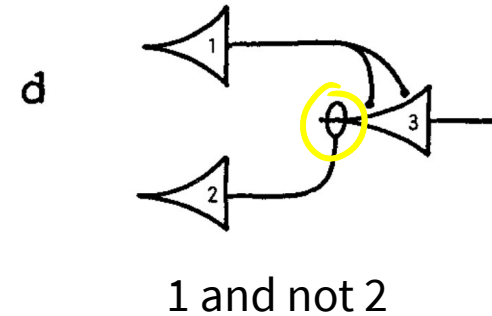
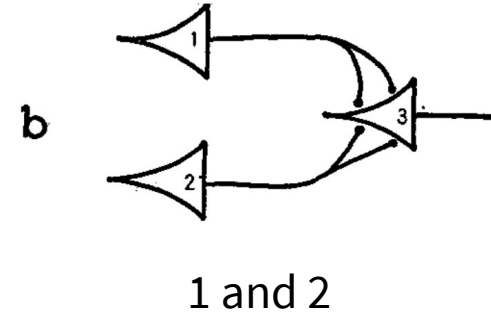
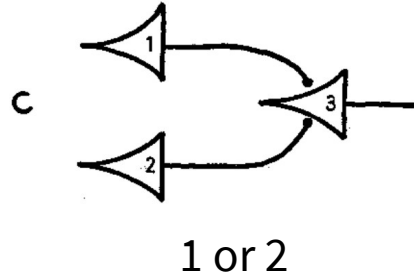
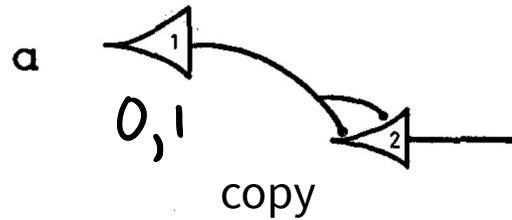
Rosenblatt
1950's



A LOGICAL CALCULUS OF THE IDEAS IMMANENT IN NERVOUS ACTIVITY

WARREN S. McCULLOCH AND WALTER PITTS

BULLETIN OF
MATHEMATICAL BIOPHYSICS
VOLUME 5, 1943



invented
symbols

All boolean functions are realizable by some network
(Later: all functions are realizable) 70's/80's